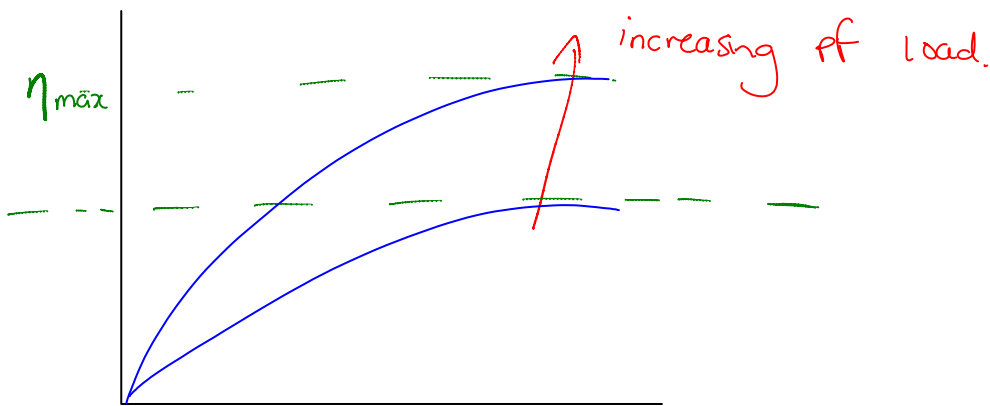


# Lecture 8

Tuesday, 1 September 2009  
4:38 PM

$$\eta = \frac{\text{output}}{\text{input}}$$

$$= \frac{V_2' I_2' \cos \phi_2}{V_2' I_2' \cos \phi_2 + P_c + (I_2')^2 R_T}$$



$$\frac{1}{\eta} = \frac{V_2' I_2' \cos \phi_2 + P_c + (I_2')^2 R_T}{V_2' I_2' \cos \phi_2}$$

$$= 1 + \frac{P_c}{V_2' I_2' \cos \phi_2} + \frac{(I_2') R_T}{V_2' \cos \phi_2}$$

$$\begin{aligned} \frac{d\left(\frac{1}{\eta}\right)}{dI_2'} &= \frac{P_c}{V_2' \cos \phi_2} - 1 \left( I_2' \right)^{-2} + \frac{R_T}{V_2' \cos \phi_2} \\ &= \frac{1}{V_2' \cos \phi_2} \left[ -\frac{P_c}{I_2'^2} + R_T \right] \end{aligned}$$

$$= 0$$

$$\therefore -\frac{P_c}{I_0^2} + R_T = 0$$

$$\Rightarrow P_c = I_0^2 R_T$$

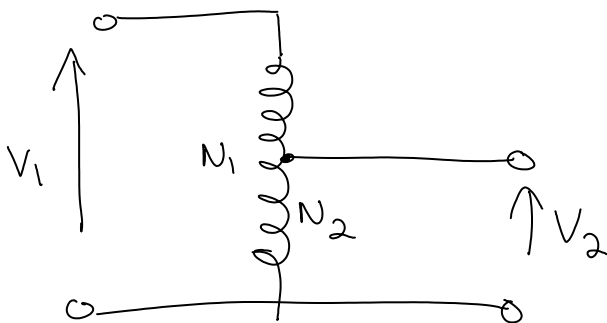
ie core losses = winding losses.

## Transformer Voltage Regulation

$$\text{Voltage Regulation} = \frac{V_2(\text{n.l.}) - V_2(\text{load})}{V_2(\text{load})}$$

as a %

## Auto-Transformer



$$\frac{V_1}{V_2} = \frac{N_1}{N_2}$$

$$\frac{I_1}{I_2} = \frac{N_2}{N_1}$$

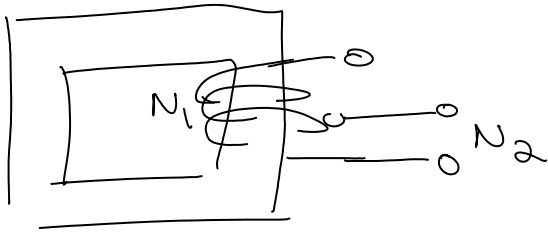
## Advantages

1. less copper required to construct the auto t-f.
2. using a slider over exposed turns can give continuously variable turns ratio. (Variac)

## Disadvantage

No galvanic isolation between 1<sup>o</sup> and 2<sup>o</sup> windings.

windings.



$$V = N \frac{d\phi}{dt}$$

The auto t/f may be used to step-up or step-down the voltage and parameters may be obtained by using the normal tests.

### Variacs

- special form of auto t/f.
- $N_2$  is continuously variable

$\therefore V_2 = \left( \frac{N_2}{N_1} \right) V_1$  is also continuously variable.